EEE4001F: Digital Signal Processing

Class Test

13 April 2017

SOLUTIONS

Name:

Student number:

Information

- The test is closed-book.
- This test has *four* questions, totalling 20 marks.
- Answer *all* the questions.
- You have 45 minutes.
- An information sheet is attached.

1. (5 marks) The input x[n] and output y[n] of a system are linked by the relation

$$y[n] = T\{x[n]\} = x[-n].$$

Answer the following questions, giving reasons:

- (a) Is the system additive?
- (b) Is the system homogeneous?
- (c) Is the system linear?
- (d) Is the system time invariant?
- (e) Is the system causal?

Suppose $y_1[n] = T\{x_1[n]\} = x_1[-n] \text{ and } y_2[n] = T\{x_2[n]\} = x_2[-n].$

(a) The response to $x[n] = x_1[n] + x_2[n]$ is

$$y[n] = T\{x_1[n] + x_2[n]\} = x_1[-n] + x_2[-n] = y_1[n] + y_2[n],$$

so the system is additive.

(b) The response to $x[n] = ax_1[n]$ is

$$y[n] = T\{ax_1[n]\} = ax_1[-n] = ay_1[n],$$

so the system is homogeneous.

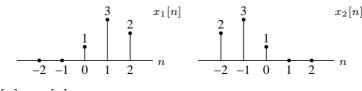
- (c) Since it is both additive and homogeneous the system is linear.
- (d) The response to $x[n] = x_1[n-p]$ is

$$y[n] = T\{x_1[n-p]\} = x_1[-(n-p)] \neq y_1[n-p]$$

so the system is not time invariant.

(e) To calculate the output y[n] at time n = 10, say, requires knowing the input x[10] which is in the future. Thus the system is not causal.

- 2. (5 marks) This question deals with convolution and time reversal.
 - (a) Consider the signals below:



Find $y[n] = x_1[n] * x_2[n]$.

- (b) Prove the time reversal property for the z-transform: if $x[n] \xleftarrow{\mathcal{Z}} X(z)$ then $x[-n] \xleftarrow{\mathcal{Z}} X(1/z)$.
- (c) Suppose $g[n] = x[n] * x_r[n]$, where $x_r[n] = x[-n]$ is the time reversal of x[n]. Show that g[n] is symmetric around the origin, or g[n] = g[-n].
- (a) Output is as follows, using the method of your choice:

(b) Suppose $x[n] \xleftarrow{\mathcal{Z}} X(z) = \sum_{n=\infty}^{\infty} x[n] z^{-n}$. We can derive the time-reversal property:

$$\mathcal{Z}\{x[-n]\} = \sum_{n=-\infty}^{\infty} x[-n]z^{-n} = \sum_{m=-\infty}^{\infty} x[m]z^m = X(1/z),$$

so $x[-n] \xleftarrow{\mathcal{Z}} X(1/z)$. Thus replacing z with 1/z in frequency corresponds to reversing the signal in the time domain.

(c) Since convolution in time is multiplication in frequency we have

$$g[n] = x[n] * x[-n] \stackrel{\mathcal{Z}}{\longleftrightarrow} X(z)X(1/z) = G(z).$$

Observing that G(z) = G(1/z) we can conclude that g[n] = g[-n]. Thus convolving a signal with its time reversal always gives a symmetric output. 3. (5 marks) A lowpass filter is described by the following system function:

$$H(z) = \frac{1-a}{1-az^{-1}}$$
 with ROC $|z| > |a|$.

- (a) Give an expression for the impulse response of the filter.
- (b) Give an expression for the frequency response of the filter. What requirements are there on a for this to exist?
- (c) Determine the value of the coefficient a such that the filter has a -3dB cutoff frequency of $\omega = \pi/4$ radians per sample.
- (a) Using the transform pair

$$a^n u[n] \quad \stackrel{\mathcal{Z}}{\longleftrightarrow} \quad \frac{1}{1 - az^{-1}} \quad \text{for } |z| > |a|$$

we obtain the impulse response

$$h[n] = (1-a)a^n u[n].$$

(b) The frequency response is

$$H(e^{j\omega}) = H(z)|_{z=e^{j\omega}} = \frac{1-a}{1-ae^{-j\omega}}.$$

This requires that the ROC include the unit circle, so |a| < 1.

(c) We require that the frequency $\omega = \pi/4$ be at the half-power point, or $|H(e^{j\pi/4})/H(e^{j0})|^2 = 1/2$. Since the DC gain is

$$H(e^{j0}) = \frac{1-a}{1-a} = 1$$

this requires finding a such that $|H(e^{j\pi/4})|^2 = 1/2$. Noting that $e^{j\pi/4} = 1 + j$ we get

$$|H(e^{j\pi/4})|^2 = H(e^{j\pi/4})H^*(e^{j\pi/4}) = \frac{1-a}{(1-a(1+j))}\frac{1-a}{(1-a(1-j))}$$
$$= \frac{1-a}{((1-a)-aj)}\frac{1-a}{((1-a)+aj)} = \frac{(1-a)^2}{(1-a)^2+a^2} = \frac{1}{2},$$

so $(1-a)^2 = a^2$ and thus a = 1/2.

4. (5 marks) The input to an anticausal LTI system is

$$x[n] = u[-n-1] + (1/2)^n u[n].$$

The Z-transform of the output of the system is

$$Y(z) = \frac{-\frac{1}{2}z^{-1}}{(1 - \frac{1}{2}z^{-1})(1 + z^{-1})}.$$

- (a) Determine the system function H(z) and specify the ROC.
- (b) Show that the ROC of Y(z) is 1/2 < |z| < 1 and find the time-domain output y[n].
- (a) Here

$$X(z) = -\frac{1}{1-z^{-1}} + \frac{1}{1-\frac{1}{2}z^{-1}} = \frac{-\frac{1}{2}z^{-1}}{(1-z^{-1})(1-\frac{1}{2}z^{-1})}$$

with ROC_x as 1/2 < |z| < 1. Given the output, we have

$$H(z) = \frac{Y(z)}{X(z)} = \frac{-\frac{1}{2}z^{-1}}{(1 - \frac{1}{2}z^{-1})(1 + z^{-1})} \frac{(1 - z^{-1})(1 - \frac{1}{2}z^{-1})}{-\frac{1}{2}z^{-1}} = \frac{1 - z^{-1}}{1 + z^{-1}}.$$

This has a pole at z = -1, so for an anticausal system we require |z| < 1 as ROC_h.

(b) We require that ROC_y contain $\operatorname{ROC}_x \cap \operatorname{ROC}_h = 1/2 < |z| < 1$. Now Y(z) has poles at z = 1/2 and z = -1, so possible ROCs are |z| < 1/2, 1/2 < |z| < 1, and |z| > 1. Thus we must have 1/2 < |z| < 1 for ROC_y . Using partial fractions we can write

$$Y(z) = \frac{1/3}{1+z^{-1}} - \frac{1/3}{1-\frac{1}{2}z^{-1}},$$

and the required inverse is

$$y[n] = -\frac{1}{3}(-1)^n u[-n-1] - \frac{1}{3}(1/2)^n u[n].$$

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Sequences $x[n], y[n]$	Transforms $X(e^{j\omega}), Y(e^{j\omega})$	Property
ax[n] + by[n]	$aX(e^{j\omega}) + bY(e^{j\omega})$	Linearity
$x[n-n_d]$	$e^{-j\omega n_d}X(e^{j\omega})$	Time shift
$e^{j\omega_0 n} x[n]$	$X(e^{j(\omega-\omega_0)})$	Frequency shi
x[-n]	$X(e^{-j\omega})$	Time reversa
nx[n]	$j \frac{dX(e^{j\omega})}{d\omega}$	Frequency dif
x[n] * y[n]	$X(e^{-j\omega})Y(e^{-j\omega})$	Convolution
x[n]y[n]	$\frac{1}{2\pi} \int_{-\pi}^{\pi} X(e^{j\theta}) Y(e^{j(\omega-\theta)}) d\theta$	Modulation

Common Fourier transform pairs

Sequence	Fourier transform	
$\delta[n]$	1	
$\delta[n-n_0]$	$e^{-j\omega n_0}$	
$1 (-\infty < n < \infty)$	$\sum_{k=-\infty}^{\infty} 2\pi \delta(\omega + 2\pi k)$	
$a^n u[n] (a < 1)$	$\frac{1}{1-ae^{-j\omega}}$	
u[n]	$\frac{1}{1-e^{-j\omega}} + \sum_{k=-\infty}^{\infty} \pi \delta(\omega + 2\pi k)$	
$(n+1)a^n u[n] (a < 1)$	$\frac{1}{(1-ae^{-j\omega})^2}$	
$\frac{\sin(\omega_C n)}{\pi n}$	$X(e^{j\omega}) = \begin{cases} 1 & \omega < \omega_c \\ 0 & \omega_c < \omega \le \pi \end{cases}$	
πn	$\prod_{i=1}^{n} (0^{i})^{i} = \begin{cases} 0 & \omega_c < \omega \le \pi \end{cases}$	
$x[n] = \begin{cases} 1 & 0 \le n \le M \\ 0 & \text{otherwise} \end{cases}$	$\frac{\sin[\omega(M+1)/2]}{\sin(\omega/2)}e^{-j\omega M/2}$	
$ \begin{bmatrix} 0 & \text{otherwise} \end{bmatrix} $	$\sin(\omega/2)$	
$e^{j\omega_0 n}$	$\sum_{k=-\infty}^{\infty} 2\pi \delta(\omega - \omega_0 + 2\pi k)$	

Common z-transform pairs

Sequence	Transform	ROC
$\delta[n]$	1	All z
u[n]	$\frac{1}{1-z^{-1}}$	z > 1
-u[-n-1]	$\frac{1}{1-z^{-1}}$	z < 1
$\delta[n-m]$	z^{-m}	All z except 0 or ∞
$a^n u[n]$	$\frac{1}{1-az^{-1}}$	z > a
$-a^n u[-n-1]$	$\frac{1}{1-az^{-1}}$	z < a
$na^nu[n]$	$\frac{az^{-1}}{(1-az^{-1})^2}$	z > a
$-na^nu[-n-1]$	$\frac{az^{-1}}{(1-az^{-1})^2}$	z < a
$\begin{cases} a^n & 0 \le n \le N-1, \\ 0 & \text{otherwise} \end{cases}$	$\frac{1-a^Nz^{-N}}{1-az^{-1}}$	z > 0
$\cos(\omega_0 n) u[n]$	$\frac{1 - \cos(\omega_0) z^{-1}}{1 - 2\cos(\omega_0) z^{-1} + z^{-2}}$	z > 1
$r^n \cos(\omega_0 n) u[n]$	$\frac{1 - r\cos(\omega_0)z^{-1}}{1 - 2r\cos(\omega_0)z^{-1} + r^2z^{-2}}$	z > r